

Lecture 19. Polynomials and linear transformations

Ex Parametrize all polynomials $p(t) \in \mathbb{P}_3$ with

$$p(-2) = 2, \quad p(0) = 4, \quad p(1) = 8.$$

Sol Consider the linear transformation $T: \mathbb{P}_3 \rightarrow \mathbb{R}^3$ given by

$$T(p(t)) = \begin{bmatrix} p(-2) \\ p(0) \\ p(1) \end{bmatrix}.$$

We solve the equation $T(p(t)) = \vec{b}$ with

$$\vec{b} = \begin{bmatrix} 2 \\ 4 \\ 8 \end{bmatrix}.$$

The standard matrix has columns $T(1), T(t), T(t^2), T(t^3)$.

$$p(t) = 1: p(-2) = 1, p(0) = 1, p(1) = 1 \Rightarrow T(1) = \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix}.$$

$$p(t) = t: p(-2) = -2, p(0) = 0, p(1) = 1 \Rightarrow T(t) = \begin{bmatrix} -2 \\ 0 \\ 1 \end{bmatrix}.$$

$$p(t) = t^2: p(-2) = 4, p(0) = 0, p(1) = 1 \Rightarrow T(t^2) = \begin{bmatrix} 4 \\ 0 \\ 1 \end{bmatrix}.$$

$$p(t) = t^3: p(-2) = -8, p(0) = 0, p(1) = 1 \Rightarrow T(t^3) = \begin{bmatrix} -8 \\ 0 \\ 1 \end{bmatrix}.$$

Hence the standard matrix is

$$A = \begin{bmatrix} 1 & -2 & 4 & -8 \\ 1 & 0 & 0 & 0 \\ 1 & 1 & 1 & 1 \end{bmatrix}.$$

Now we can convert the equation $T(p(t)) = \vec{b}$ into a matrix equation $A\vec{x} = \vec{b}$ by setting $\vec{x} = [p(t)]$.

$$\left[\begin{array}{cccc|c} 1 & -2 & 4 & -8 & 2 \\ 1 & 0 & 0 & 0 & 4 \\ 1 & 1 & 1 & 1 & 8 \end{array} \right] \xrightarrow{\text{RREF}} \left[\begin{array}{cccc|c} 1 & 0 & 0 & 0 & 4 \\ 0 & 1 & 0 & 2 & 3 \\ 0 & 0 & 1 & -1 & 1 \end{array} \right]$$

A
 \vec{b}

$$\Rightarrow \begin{cases} x_1 = 4 \\ x_2 + 2x_4 = 3 \\ x_3 - x_4 = 1 \end{cases} \Rightarrow \begin{cases} x_1 = 4 \\ x_2 = 3 - 2x_4 \\ x_3 = 1 + x_4 \end{cases} \Rightarrow \vec{x} = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 4 \\ 3 - 2C \\ 1 + C \\ C \end{bmatrix}$$

$x_4 = C$

As we set $\vec{x} = [p(t)]$, we find

$$p(t) = 4 + (3 - 2C)t + (1 + C)t^2 + Ct^3$$

Note (1) This example demonstrates polynomial interpolation, which refers to the process of finding polynomials whose graphs pass through specific points.

(2) We may write the solution as

$$\begin{aligned} p(t) &= (4 + 3t + t^2) + C(-2t + t^2 + t^3) \\ &= (4 + 3t + t^2) + Ct(t-1)(t+2). \end{aligned}$$

The first polynomial $4 + 3t + t^2$ is given by the last column in the RREF, whereas the second polynomial $t(t-1)(t+2)$ has roots at $t = \underline{-2, 0, 1}$.
 specified inputs

Ex Find the polynomial solution of the differential equation

$$p(t) + 2p'(t) + 3p''(t) = 2t^2 + 3t + 5.$$

Sol Consider the linear transformation $T: \mathbb{P}_2 \rightarrow \mathbb{P}_2$ given by

$$T(p(t)) = p(t) + 2p'(t) + 3p''(t).$$

We solve the equation $T(p(t)) = 2t^2 + 3t + 5$.

The standard matrix has columns $[T(1)]$, $[T(t)]$, $[T(t^2)]$.

* $T(1)$, $T(t)$, $T(t^2)$ themselves are not column vectors

$$p(t) = 1: p'(t) = 0, p''(t) = 0 \Rightarrow T(1) = 1 + 2 \cdot 0 + 3 \cdot 0 = 1$$

$$p(t) = t: p'(t) = 1, p''(t) = 0 \Rightarrow T(t) = t + 2 \cdot 1 + 3 \cdot 0 = t + 2$$

$$p(t) = t^2: p'(t) = 2t, p''(t) = 2 \Rightarrow T(t^2) = t^2 + 2 \cdot 2t + 3 \cdot 2 = t^2 + 4t + 6$$

Hence the standard matrix is

$$A = \begin{bmatrix} 1 & 2 & 6 \\ 0 & 1 & 4 \\ 0 & 0 & 1 \end{bmatrix}.$$

* Since T takes values in \mathbb{P}_2 , each coordinate vector has 3 entries (with standard basis of \mathbb{P}_2 given by $1, t, t^2$)

Now we can convert the equation $T(p(t)) = 2t^2 + 3t + 5$ into a matrix equation $A\vec{x} = [2t^2 + 3t + 5]$ by setting $\vec{x} = [p(t)]$.

$$\begin{bmatrix} 1 & 2 & 6 & | & 5 \\ 0 & 1 & 4 & | & 3 \\ 0 & 0 & 1 & | & 2 \end{bmatrix} \xrightarrow{\text{RREF}} \begin{bmatrix} 1 & 0 & 0 & | & 3 \\ 0 & 1 & 0 & | & -5 \\ 0 & 0 & 1 & | & 2 \end{bmatrix}$$

A

$$\Rightarrow x_1 = 3, x_2 = -5, x_3 = 2$$

As we set $\vec{x} = [p(t)]$, we find $p(t) = \boxed{3 + 5t + 2t^2}$